



Pointshop 3D

An Interactive System for Point-based
Surface Editing

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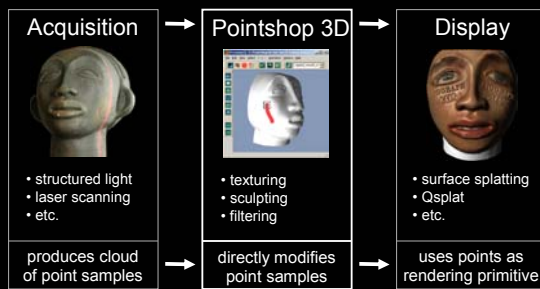


ETH Zürich

Outline

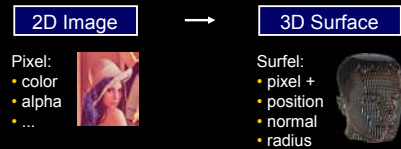
- Introduction
- Pointshop3D system components
 - Point cloud parameterization
 - Dynamic sampling
 - Editing operators
- Demo
- Conclusions

Point-Based 3D Content Creation



Pointshop 3D

- Generalizes 2D photo editing concepts and functionality to 3D point-sampled surfaces

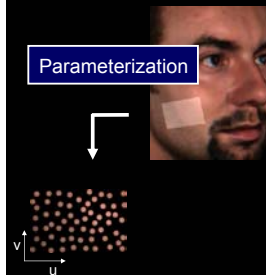


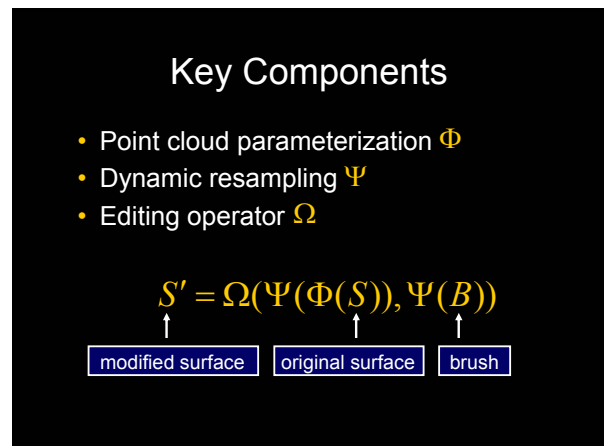
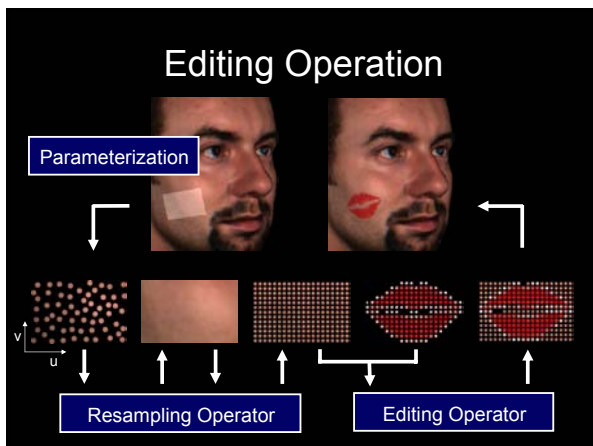
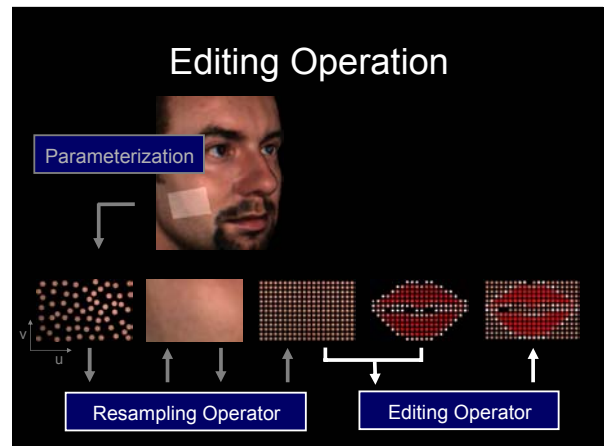
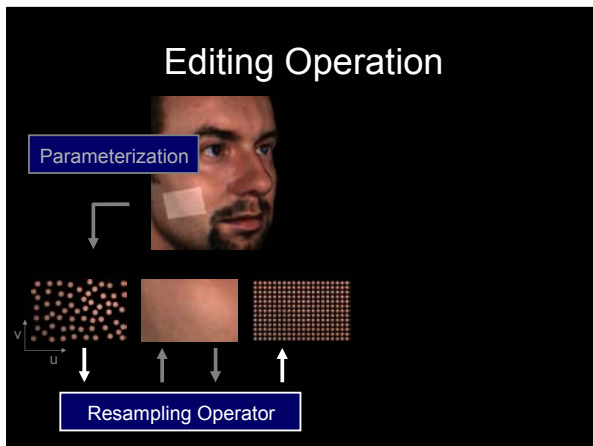
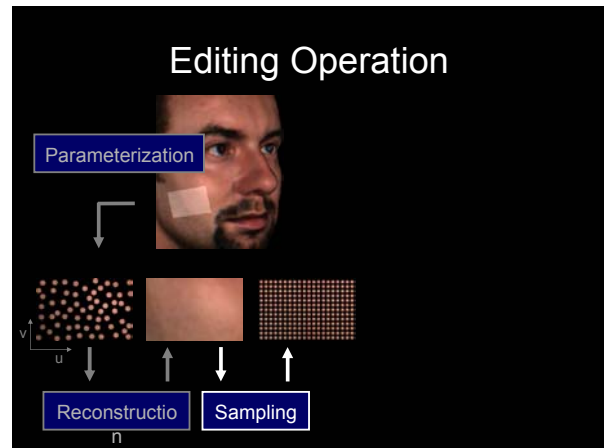
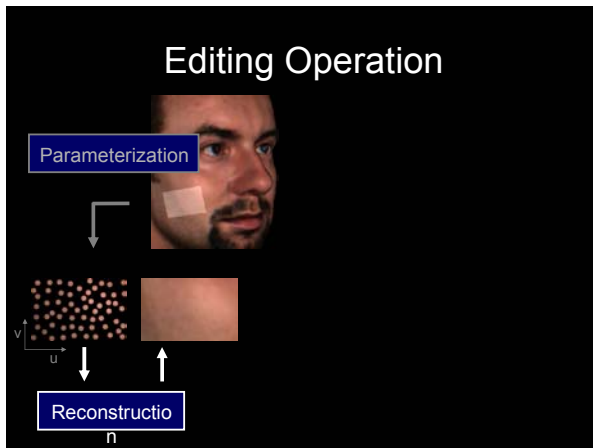
⇒ Geometry editing: modify 3D positions and normals, e.g. sculpting and filtering

Editing Operation



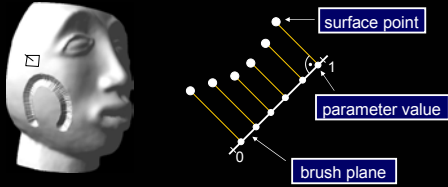
Editing Operation





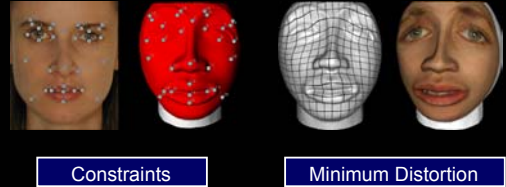
Point Cloud Parameterization

- Brush interaction
 - Parameterize by orthogonal projection



Point Cloud Parameterization

- Selection interaction
 - Constrained minimum distortion parameterization



Point Cloud Parameterization

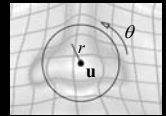
- Minimize objective function

$$C(X) = \underbrace{\sum_{j \in M} (X(\mathbf{p}_j) - \mathbf{x}_j)^2}_{\text{fitting constraints}} + \underbrace{\varepsilon \int_P \gamma(\mathbf{u}) d\mathbf{u}}_{\text{distortion}}$$

Point Cloud Parameterization

- Measuring distortion

$$\gamma(\mathbf{u}) = \int_{\theta} \left(\frac{\partial^2}{\partial r^2} X_{\mathbf{u}}(\theta, r) \right)^2 d\theta$$



- Integrates squared curvature using local polar re-parameterization

$$X_{\mathbf{u}}(\theta, r) = X \left(\mathbf{u} + r \begin{bmatrix} \cos(\theta) \\ \sin(\theta) \end{bmatrix} \right)$$

Point Cloud Parameterization

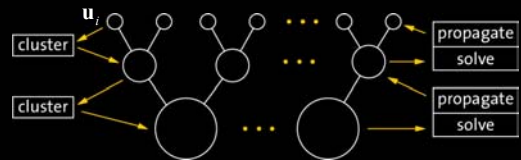
- Discrete formulation:
 - Approximate second derivative with divided differences
 - Discretize integral using normal sections based on k-nearest neighbors

$$\gamma(\mathbf{u}_i) \approx \sum_{j \in N_i} \underbrace{\left(\frac{\partial X(\mathbf{u}_i)}{\partial \mathbf{v}_j} - \frac{\partial X(\mathbf{u}_j)}{\partial \tilde{\mathbf{v}}_j} \right)^2}_{\text{discrete curvature}}$$



Point Cloud Parameterization

- Discrete formulation:
 - Leads to a linear least squares system
 - Efficiently solved using multi-grid approach



Reconstruction

- Parameterized scattered data approximation

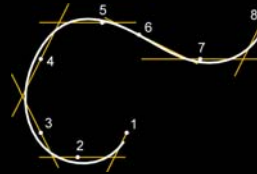
$$S(\mathbf{u}) = \frac{\sum_i \Phi_i(\mathbf{u}) r_i(\mathbf{u})}{\sum_i r_i(\mathbf{u})}$$

Diagram illustrating the reconstruction formula with labels:

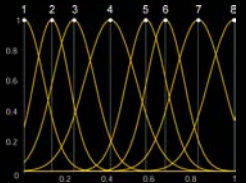
- fitting functions** (points to $\Phi_i(\mathbf{u})$)
- weight functions** (points to $r_i(\mathbf{u})$)
- normalization factor** (points to the denominator $\sum_i r_i(\mathbf{u})$)

- Compute local fitting functions using local parameterization
- Map to global parameterization using global parameter coordinates of neighboring points

Reconstruction



reconstruction with linear fitting functions



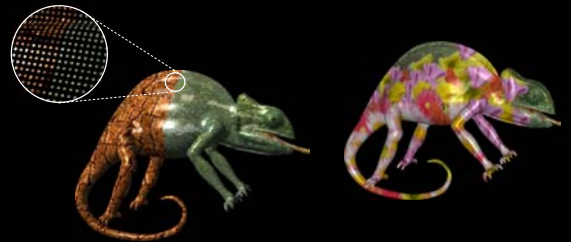
Gaussian weight functions in parameter space

Sampling

- Three sampling strategies:
 - Sample at the original surface points
 - Sample at the brush points
 - Adaptive sampling, i.e. sample at surface or brush points depending on the local sampling density
- Antialiasing
 - Band-limit the weight functions (Gaussians) before sampling using Gaussian low-pass filter
 - ⇒ Surface splatting framework

Editing Operators

- Painting
 - Texture, material properties, transparency



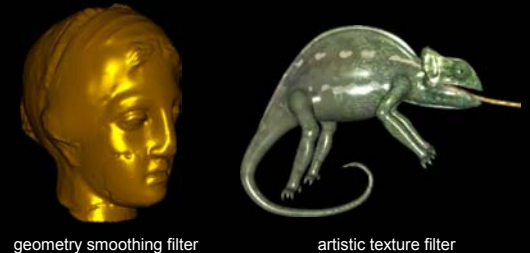
Editing Operators

- 3D Sculpting



Editing Operators

- Filtering



Demo

Discussion

- Efficient point-based surface resampling
- Robust reconstruction based on k-nearest neighbors requires:
 - No outliers
 - Sufficiently high, roughly uniform sampling density
 - Little noise
- Geometry editing is restricted to displacements

Ongoing & Future Work

- Model cleaning
 - User-guided \Rightarrow provide appropriate tools
 - Automatic pre-process
- More general modeling functionality
 - Free-form deformation
 - Physics-based modeling
- Texture synthesis and transfer

Conclusion

- Pointshop3D provides sophisticated editing operations on point-sampled surfaces
 - \Rightarrow points are a versatile and powerful graphics primitive
- Software release in fall 2002 on

www.pointshop3d.com

Acknowledgements

- Tim Weyrich
- Martin Roth
- CGL, ETH Zürich
- European Graduate Program on Combinatorics, Geometry and Computation
- MERL

pointshop

